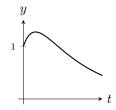
- 1. [2360/071224 (10 pts)] Write the word TRUE or FALSE as appropriate. No work need be shown. No partial credit given.
 - (a) If s > 0, then $\int_0^\infty t^5 e^{-st} \, \mathrm{d}t = \frac{5}{s^5}$.
 - (b) The solutions to the harmonic oscillator equation $2\ddot{x} + 7p\dot{x} + 6x = 12\cos\sqrt{3}t$ will grow without bound for only a single real value of p.
 - (c) The differential equation $y'' + y \cos y = -5$ describes a conservative system.

(d)
$$\mathscr{L}^{-1}\left\{\frac{3}{s^2+6s+12}\right\} = e^{-3t}\sin\sqrt{3t}$$

(e) The following graph depicts the solution of y'' + 6y' + 5y = 0, y(0) = 1, y'(0) = 0.



SOLUTION:

- (a) FALSE $\int_0^\infty t^5 e^{-st} dt = \mathscr{L}\left\{t^5\right\} = \frac{5!}{s^6}$
- (b) **TRUE** Since $\omega_0 = \sqrt{6/2} = \sqrt{3} = \omega_f$, the system can be in resonance if it is undamped. This will occur if and only if p = 0.
- (c) **TRUE** It is in the form $\ddot{y} + V'(y) = 0$ with $V'(y) = y \cos y + 5$.
- (d) FALSE $\mathscr{L}^{-1}\left\{\frac{3}{s^2+6s+12}\right\} = \sqrt{3}\mathscr{L}^{-1}\left\{\frac{\sqrt{3}}{(s+3)^2+(\sqrt{3})^2}\right\} = \sqrt{3}e^{-3t}\sin\sqrt{3}t$
- (e) FALSE The graph has a positive slope at t = 0 but the initial condition is y'(0) = 0.

2. [2360/071224 (20 pts)] Consider the linear operator $L(\vec{y}) = y''' - 6y'' + 13y' - 10y$.

- (a) (12 pts) If $y(t) = e^{2t}$ is a solution of $L(\vec{\mathbf{y}}) = 0$, find the general solution of $L(\vec{\mathbf{y}}) = 0$.
- (b) (8 pts) Convert the initial value problem $L(\vec{y}) = e^{-t} + 5$, y(0) = y'(0) = y''(0) = 0, into a system of first order initial value problems. If possible, write the system using matrices and vectors. If not, explain why not.

SOLUTION:

(a) Since e^{2t} is a solution to the differential equation, r = 2 is solution to the characteristic equation $r^3 - 6r^2 + 13r - 10 = 0$. Synthetic division then gives

	1	-6	13	-10
2		2	-8	10
	1	-4	5	0

which gives the characteristic equation as $(r-2)(r^2 - 4r + 5) = 0$. Using the quadratic formula shows that the other two roots are $r = 2 \pm i$. From this the general solution is $y(t) = e^{2t} (c_1 + c_2 \cos t + c_3 \sin t)$.

(b) Let $x_1 = y, x_2 = y', x_3 = y''$. Then

$$\begin{aligned} x_1' &= y' = x_2 \\ x_2' &= y'' = x_3 \\ x_3' &= y''' = e^{-t} + 5 + 10y - 13y' + 6y'' = 10x_1 - 13x_2 + 6x_3 + e^{-t} + 5 \end{aligned}$$

and since the equation is linear

$$\begin{bmatrix} x_1' \\ x_2' \\ x_3' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 10 & -13 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ e^{-t} + 5 \end{bmatrix}, \begin{bmatrix} x_1(0) \\ x_2(0) \\ x_3(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- 3. [2360/071224 (30 pts)] A 1-kg mass is attached to a spring. The system is hooked up to a mechanism that imparts a damping force equal to eight times the instantaneous velocity of the mass. The entire apparatus is lying horizontally on a table.
 - (a) (3 pts) You have been told that a force of 10 N is required to stretch the spring 0.5 m. Find the restoring (spring) constant and write the differential equation that governs the motion of the mass, assuming the oscillator is unforced.
 - (b) (5 pts) Verify that the roots of the characteristic equation associated with the differential equation in part (a) are $-4 \pm 2i$ and write the equation of motion for the unforced oscillator, that is, the solution to the differential equation in part (a).
 - (c) (3 pts) Is the oscillator overdamped, underdamped or critically damped? Justify your answer.
 - (d) (15 pts) Now suppose the oscillator is subjected to an external force of $f(t) = 32 \sin 2t + 16 \cos 2t$. If the mass is initially (t = 0) at rest at the equilibrium position, where is the mass when $t = \pi/4$?
 - (e) (4 pts) If they exist, identify the transient and steady state solutions in part (d). If one or both do not exist, explain why not.

SOLUTION:

- (a) If 10 N are required to stretch the spring 0.5 m, the restoring constant is 10/0.5 = 20 N/m. If x(t) is the displacement of the mass from its equilibrium position, the differential equation governing the motion is $\ddot{x} + 8\dot{x} + 20x = 0$.
- (b) The characteristic equation is $r^2 + 8r + 20 = 0 \implies r = \frac{-8 \pm \sqrt{8^2 4(1)(20)}}{2} = \frac{-8 \pm 4i}{2} = -4 \pm 2i$ so that the equation of motion is $x(t) = e^{-4t} (c_1 \cos 2t + c_2 \sin 2t)$.
- (c) Since $b^2 4mk = -16 < 0$, the oscillator is underdamped.
- (d) From part (b) we have $x_h(t) = e^{-4t} (c_1 \cos 2t + c_2 \sin 2t)$. We use the Method of Undetermined Coefficients to find the particular solution.

$$x_p = A\cos 2t + B\sin 2t$$

 $\ddot{x}_p + 8\dot{x}_p + 20x_p = -4A\cos 2t - 4B\sin 2t + 8\left(-2A\sin 2t + 2B\cos 2t\right) + 20\left(A\cos 2t + B\sin 2t\right) = 32\sin 2t + 16\cos 2t$ $(16A + 16B)\cos 2t + (16B - 16A)\sin 2t = 32\sin 2t + 16\cos 2t$

 $x(t) = e^{-4t} \left(c_1 \cos 2t + c_2 \sin 2t \right) + \frac{3}{2} \sin 2t - \frac{1}{2} \cos 2t \qquad \text{apply initial conditions}$

$$x(0) = c_1 - \frac{1}{2} = 0 \implies c_1 = \frac{1}{2}$$

$$x'(t) = e^{-4t} \left(-\sin 2t + 2c_2 \cos 2t \right) - 4e^{-4t} \left(\frac{1}{2} \cos 2t + c_2 \sin 2t \right) + 3\cos 2t + \sin 2t$$

$$x'(0) = 2c_2 - 2 + 3 = 0 \implies c_2 = -\frac{1}{2}$$

$$x(t) = \frac{1}{2}e^{-4t} \left(\cos 2t - \sin 2t \right) + \frac{3}{2}\sin 2t - \frac{1}{2}\cos 2t$$

$$x(\pi/4) = \frac{1}{2}e^{-4(\pi/4)} \left(\cos \frac{\pi}{2} - \sin \frac{\pi}{2} \right) + \frac{3}{2}\sin \frac{\pi}{2} - \frac{1}{2}\cos \frac{\pi}{2} = \frac{1}{2} \left(3 - e^{-\pi} \right)$$
In solution: $\frac{1}{2}e^{-4t} \left(\cos 2t - \sin 2t \right)$; steady state solution: $\frac{3}{2}\sin 2t - \frac{1}{2}\cos 2t$

(e) Transient solution: $\frac{1}{2}e^{-4t}(\cos 2t - \sin 2t)$; steady state solution: $\frac{3}{2}\sin 2t - \frac{1}{2}\cos 2t$

4. [2360/071224 (15 pts)] Use variation of parameters to find the general solution of $2\frac{d^2y}{dt^2} - 4\frac{dy}{dt} - 6y = 72te^{2t}$. Feel free to use the following formula if desired:

$$\int t e^{at} \, \mathrm{d}t = \frac{(at-1)e^{at}}{a^2} + C$$

SOLUTION:

Begin by getting the equation into the standard form: $y'' - 2y' - 3y = 36te^{2t}$. The characteristic equation for the associated homogeneous equation is $r^2 - 2r - 3 = (r - 3)(r + 1) = 0 \implies r = -1, 3 \implies y_1 = e^{-t}, y_2 = e^{3t}$. Let $y_p = v_1y_1 + v_2y_2$.

$$W\left[e^{-t}, e^{3t}\right] = \begin{vmatrix} e^{-t} & e^{3t} \\ -e^{-t} & 3e^{3t} \end{vmatrix} = 4e^{2t}$$
$$v_1 = \int \frac{-y_2 f}{W\left[e^{-t}, e^{3t}\right]} dt = \int \frac{-e^{3t} \left(36te^{2t}\right)}{4e^{2t}} dt = -9 \int te^{3t} dt = -9 \left[\frac{1}{9}(3t-1)e^{3t}\right] = e^{3t}(1-3t)$$
$$v_2 = \int \frac{y_1 f}{W\left[e^{-t}, e^{3t}\right]} dt = \int \frac{e^{-t} \left(36te^{2t}\right)}{4e^{2t}} dt = 9 \int te^{-t} dt = -9e^{-t}(t+1)$$
$$y_p = e^{3t}(1-3t)e^{-t} - 9e^{-t}(t+1)e^{3t} = e^{2t}(1-3t-9t-9) = -4e^{2t}(3t+2)$$
$$y = c_1e^{-t} + c_2e^{3t} - 4e^{2t}(3t+2)$$

- 5. [2360/071224 (25 pts)] The following problems require the use of the Method of Undetermined Coefficients. **Do not solve** for the coefficients in parts (a) and (b).
 - (a) (5 pts) Find the form of the particular solution when solving $w'' + 4w' 5w = 2360 + 2\sin 3t + 3\cos 2t$.
 - (b) (5 pts) Find the form of the particular solution if the characteristic equation is $r^4 r^3 = 0$ and the forcing function (right hand side of the differential equation) is $f(t) = t^3 7e^{-t} + 2$.
 - (c) (15 pts) Solve the initial value problem $z'' 6z' + 9z = 6e^{3t}$, z(0) = 3, z'(0) = 12.

SOLUTION:

- (a) $r^2 + 4r 5 = (r+5)(r-1) = 0 \implies r = -5, 1 \implies$ basis for the solution space of homogeneous problem is $\{e^{-5t}, e^t\}$. Thus, $y_p = A \sin 3t + B \cos 3t + C \sin 2t + D \cos 2t + E$
- (b) $r^3(r-1) = 0 \implies r = 0$, multiplicity 3 and r = 1 so a basis for the solution space is $\{1, t, t^2, e^t\}$. Thus, $y_p = t^3 \left(At^3 + Bt^2 + Ct + D\right) + Ee^{-t} = At^6 + Bt^5 + Ct^4 + Dt^3 + Ee^{-t}$
- (c) $r^2 6r + 9 = (r 3)^2 = 0 \implies r = 3$ multiplicity $2 \implies z_h = c_1 e^{3t} + c_2 t e^{3t}$. The initial guess for the particular solution is Ae^{3t} but this must be multiplied by t^2 so that none of the guess is a solution to the homogeneous problem. Thus $z_p = At^2 e^{3t}$ and

$$\begin{aligned} z_p'' - 6z_p' + 9z_p &= A \left(9t^2 e^{3t} + 12t e^{3t} + 2e^{3t}\right) - 6A \left(3t^2 e^{3t} + 2t e^{3t}\right) + 9At^2 e^{3t} = 6e^{3t} \\ & 2Ae^{3t} = 6e^{3t} \implies A = 3 \implies z_p = 3t^2 e^{3t} \\ z(t) &= z_h(t) + z_p(t) = c_1 e^{3t} + c_2 t e^{3t} + 3t^2 e^{3t} \\ z(0) &= c_1 = 3 \end{aligned}$$
$$z(t) &= 3e^{3t} + c_2 t e^{3t} + 3t^2 e^{3t} \implies z'(t) = 9e^{3t} + c_2 \left(3t e^{3t} + e^{3t}\right) + 3 \left(3t^2 e^{3t} + 2t e^{3t}\right) \\ z'(0) &= 9 + c_2 = 12 \implies c_2 = 3 \\ z(t) &= 3e^{3t} \left(t^2 + t + 1\right) \end{aligned}$$